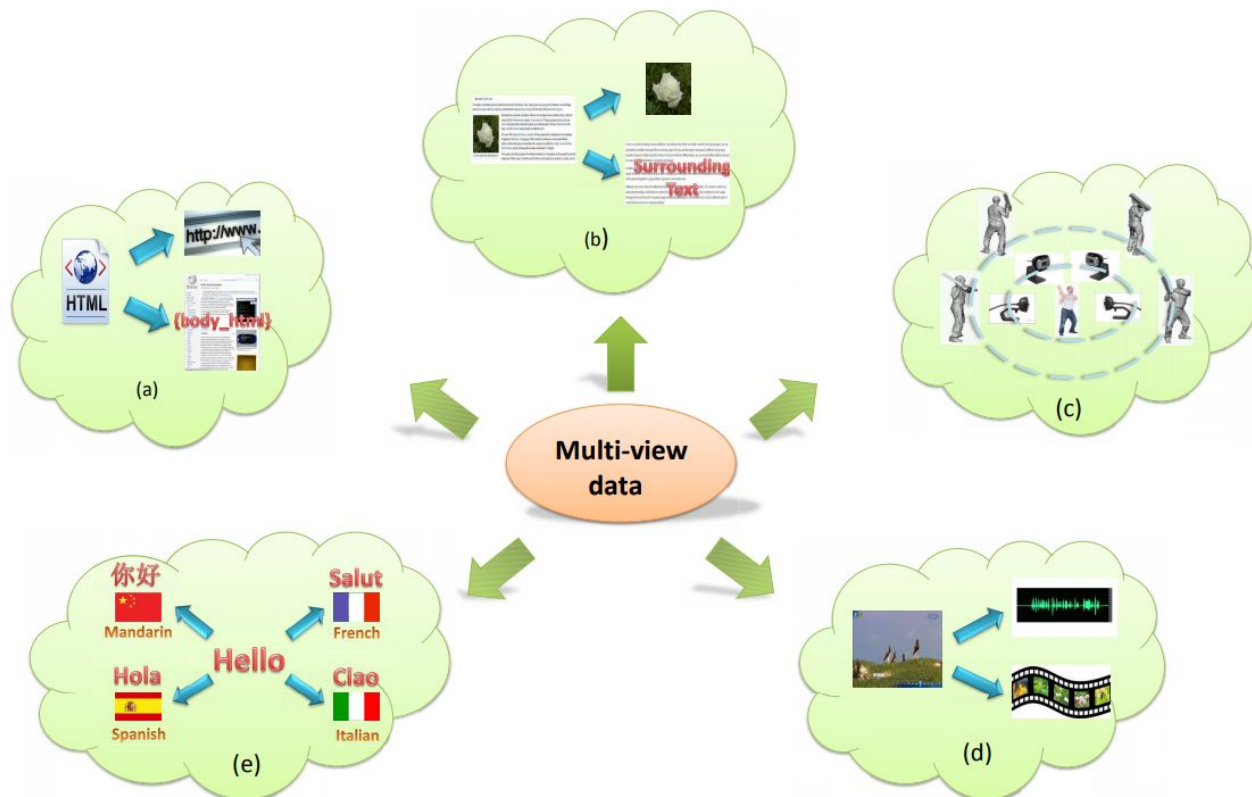


A Probabilistic Framework for Multi-view Feature Learning with Many-to-many Associations via Neural Networks

Akifumi Okuno, Tetsuya Hada, Hidetoshi Shimodaira

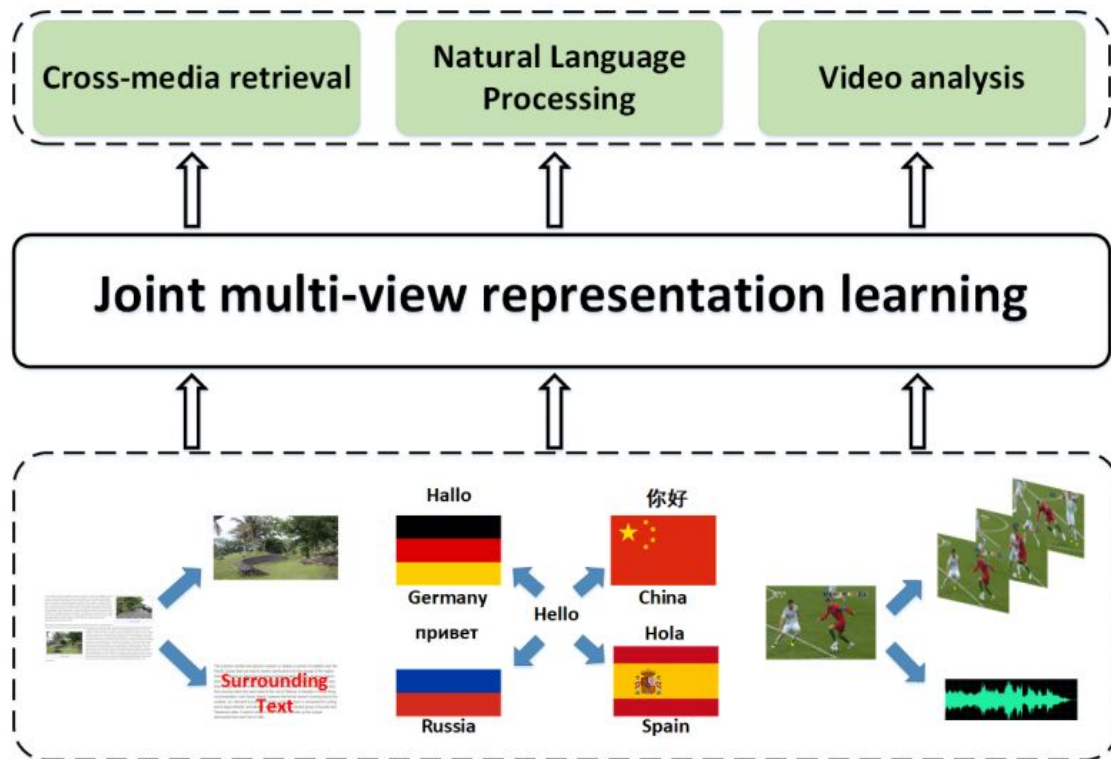
Presented by: Zhun Liu

What is Multi-view Data?

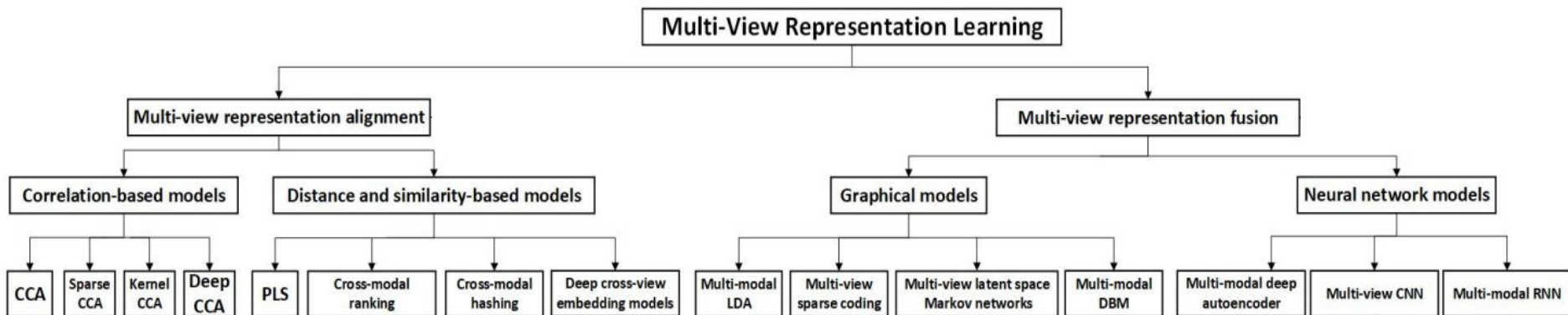


Multi-view Representation Learning

- CCA
- DCCA
- Cycle-translation
- Multimodal skip-gram
- Graph Convolution
- ...



Multi-view Representation Learning



A nice survey if you want to dig into it:

A Survey of Multi-View Representation Learning

<https://arxiv.org/pdf/1610.01206.pdf>

What previous models achieve

CCA: Paired-data, one-to-one associations, linear relationships

DCCA: Paired-data, one-to-one associations, **non-linear relationships**

CDMCA: Graph data, **many-to-many associations**, linear relationships

...

Authors of this paper: We need a **many-to-many, non-linear** model!

PMvGE: the Model Input

Data points from D different views:

$$\mathbf{X} = \{(x_1, d_1), (x_2, d_2), \dots, (x_n, d_n)\}$$

$$d_i \in \{1, 2, \dots, D\}$$

Observed links (link weights) between the data points

$$\mathbf{W} = \{w_{ij}, (i, j) \in [n] \times [n]\}$$

PMvGE: the Model Parameters

We first define a similarity score parametrized by neural nets and a symmetric matrix α to regulate the connections between views

$$\mu_{ij} = \alpha^{(d_i, d_j)} \cdot \exp(\langle f_{\psi_i}^{(d_i)}(x_i), f_{\psi_j}^{(d_j)}(x_j) \rangle)$$

These scores are normalized to get association probabilities

$$P(e_t = (x_i, x_j) | \{x_k\}_{k=1}^N) := \frac{\mu_{ij}}{\sum_{i \neq j} \mu_{ij}}$$

PMvGE: the Generative Modelling Process

First we draw a random non-negative integer T from a particular Poisson process

$$T \sim \text{Poisson}(\lambda), \lambda := \sum_{i \neq j} \mu_{ij}$$

We then draw from the link distribution we have defined previously T times

$$s_t \sim P(e_t = (x_i, x_j) | \{x_k\}_{k=1}^N), t = 1, \dots, T$$

Then w_{ij} is defined as the number of times link (x_i, x_j) appeared

$$w_{ij} := \sum_{i=1}^T \mathbb{I}_{e_t=(x_i, x_j)}$$

PMvGE: the Objective Function

From previous generative process, it turns out w_{ij} follows a Poisson distribution:

$$w_{ij} \sim \text{Poisson}(\mu_{ij})$$

Hence it has the PMF

$$P(w_{ij}) = \mu_{ij}^{w_{ij}} \cdot \frac{\exp(-\mu_{ij})}{w_{ij}!}$$

Taking the log likelihood for the entire dataset we have

$$\begin{aligned} \log P(\{w_{ij}\}, (i, j) \in \mathcal{I}_n) &= \log \prod_{(i, j) \in \mathcal{I}_n} P(w_{ij}) \\ &= \sum_{(i, j) \in \mathcal{I}_n} w_{ij} \log \mu_{ij} - \mu_{ij} - \log(w_{ij}!) \end{aligned}$$

PMvGE: the Objective Function - continued

For optimization purposes, we could throw away the last term that is not related to parameters

$$\ell_n(\{x_k\}, \{w_{ij}\} | \alpha, \psi) = \sum_{(i,j) \in \mathcal{I}_n} w_{ij} \log \mu_{ij} - \mu_{ij}$$

Then we can maximize this objective to perform MLE of model parameters.

Yay! Mission accomplished!

```
loss.backward()
```

```
optimizer.step()
```

PMvGE: Optimization

- Can we go ahead and perform SGD on the log likelihood?

No, because that way we cannot enforce symmetry of α

We need an alternating iterative algorithm that optimizes α, ψ .

First fix α and do SGD on ψ : some mini-batch sampling details involved

Then update α analytically: see equation (11) in the paper

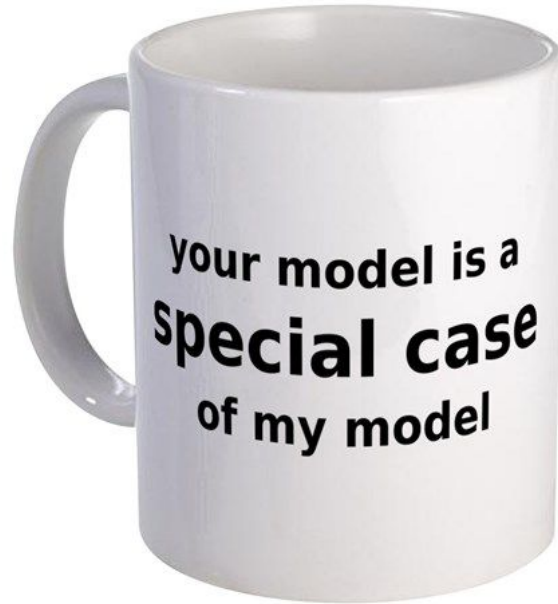
PMvGE: “Your model is a special case of my model”

CCA...

MLP...

CDMCA...

DCCA...



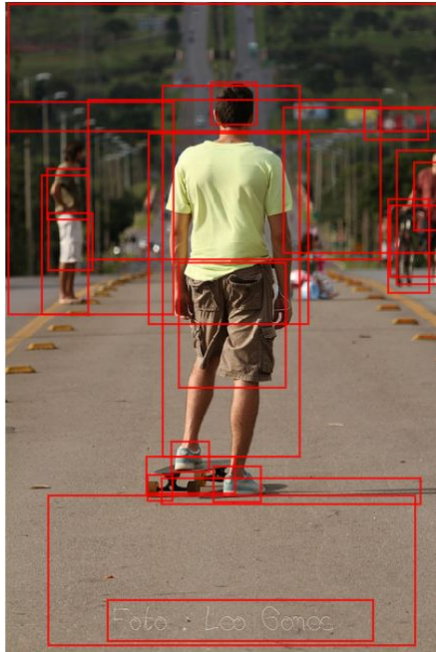
Multi-Entity Variational Autoencoder

Charlie Nash, S. M. Ali Eslami, Chris Burgess, Irina Higgins, Daniel Zoran,
Theophane Weber, Peter Battaglia

Presented by: Zhun Liu

What if our views are not naturally separated?

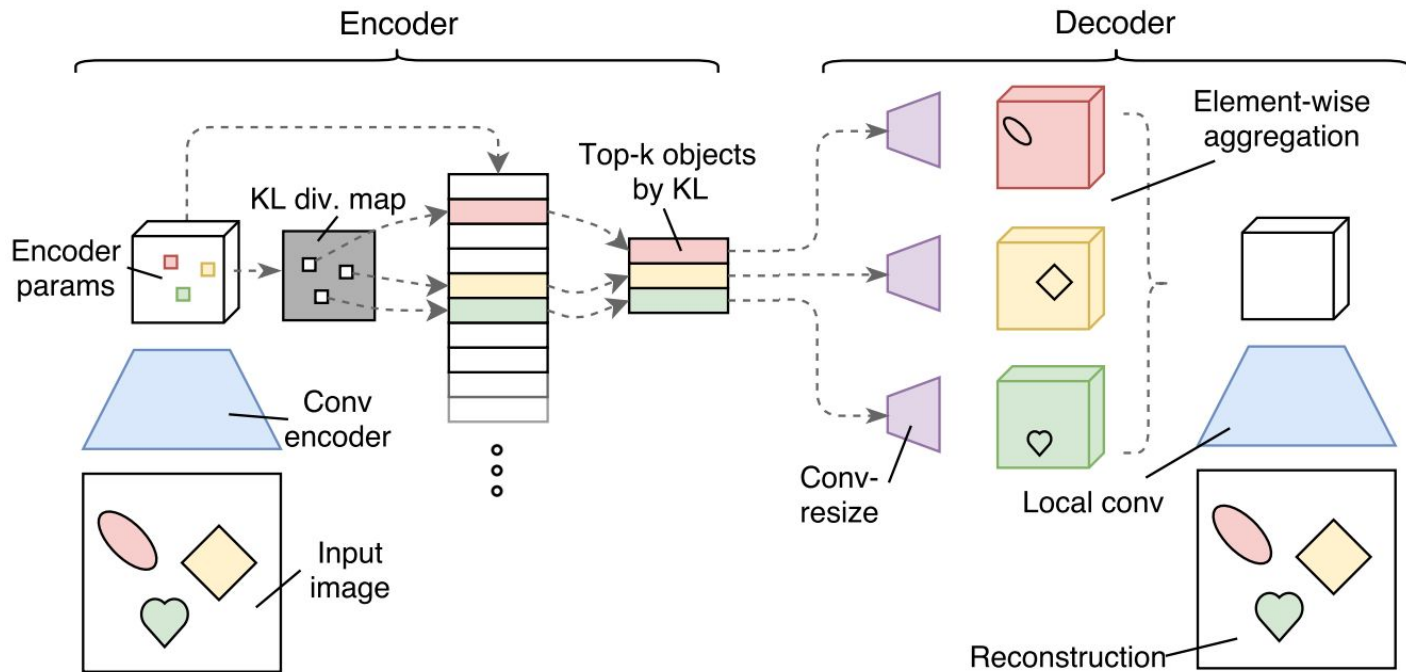
E.g. We have bounding boxes of objects and we treat them each as a view



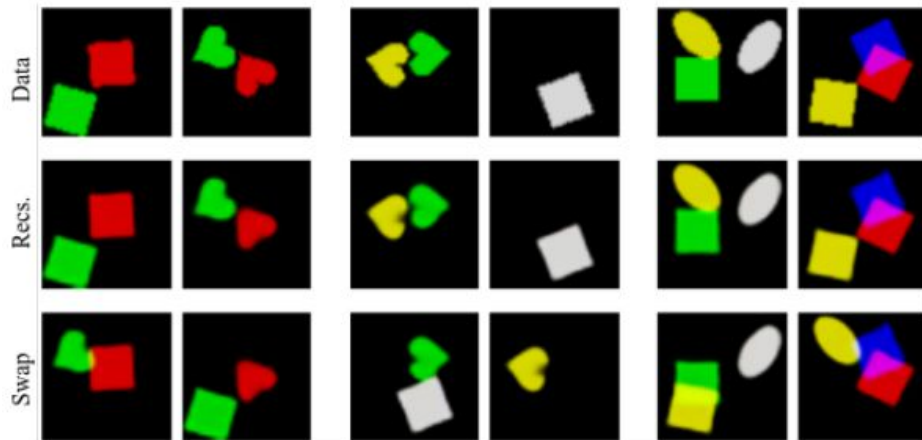
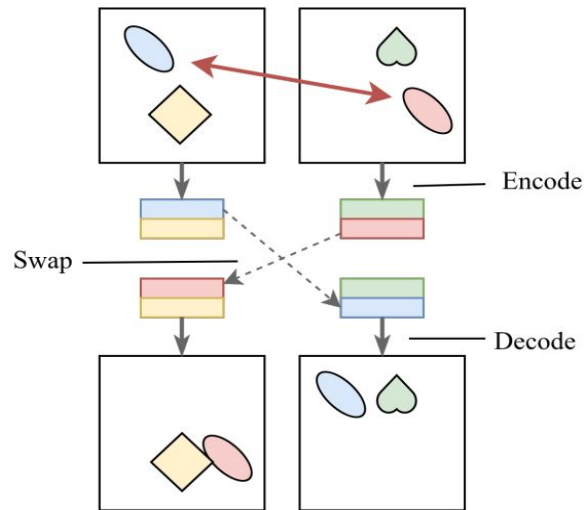
What if we don't have bounding boxes?

What if our views are just mixed together?

Multi-Entity VAE: Picking Multiple Representations



Multi-Entity VAE: Disentangling Between Objects



Thanks!